# 類神經

LMS Learning

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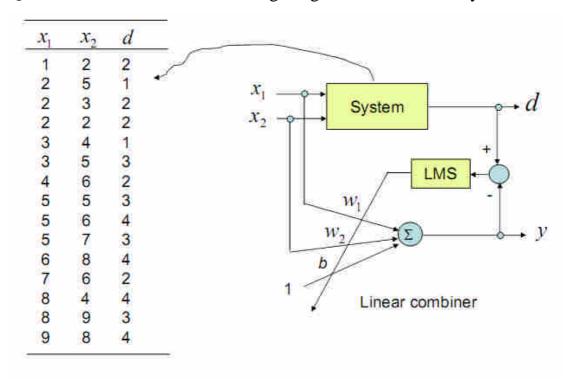
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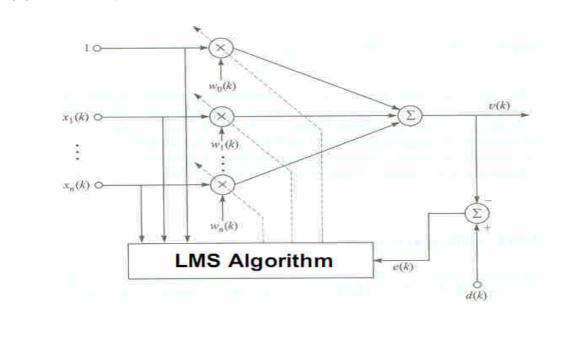
# 第一題題目

# **Problem 1**

Q1: Use LMS to learn the following weights and simulate it by Matlab



# (1) LMS 架構圖:



#### (2) 數學方程式:

$$\begin{split} \nabla_{\mathbf{w}} J(\mathbf{w}) &\approx \frac{1}{2} \frac{\partial e^2(k)}{\partial \mathbf{w}} \bigg|_{\mathbf{w} = \mathbf{w}(k)} \\ &= \frac{1}{2} \frac{\partial}{\partial \mathbf{w}(k)} \Big[ d^2(k) - 2d(k) \mathbf{x}^T(k) \mathbf{w}(k) + \mathbf{w}^T(k) \mathbf{x}(k) \mathbf{x}^T(k) \mathbf{w}(k) \Big] \\ &= -d(k) \mathbf{x}(k) + \mathbf{x}(k) \mathbf{x}^T(k) \mathbf{w}(k) = -d(k) \mathbf{x}(k) + \mathbf{w}^T(k) \mathbf{x}(k) \mathbf{x}(k) \\ &= - \underbrace{[d(k) - \mathbf{w}^T(k) \mathbf{x}(k)]}_{e(k)} \mathbf{x}(k) = -e(k) \mathbf{x}(k) \end{split}$$

Therefore, the learning rule for updating the weights using the steepest-descent method as

$$w(k+1) = w(k) + \mu[-\nabla_w J(w)] = w(k) + \mu e(k)x(k)$$

Where  $\mu$  is learning rate with  $0 < \mu < \frac{2}{\lambda_{max}}$  or  $0 < \mu < \frac{2}{\operatorname{trace}\{C_x\}}$ 

#### (3) 設定步驟:

Step 1. Set k = 1, initialize the synaptic weight vector w(k = 1), and select values for  $\mu_0$  and  $\tau$ .

Step 2. Compute the learning rate parameter as

$$\mu(k) = \frac{\mu_0}{1 + k/\tau}$$
  $\tau$ : searching time constant 100 <=  $\tau$  <= 500

Step 3. Compute the error

$$c(k) = d(k) - \sum_{h=1}^{n} w_h(k)x_h(k)$$

Step 4. Update the synaptic weights  $w_i(k+1) = w_i(k) + \mu(k)e(k)x_i(k)$ , for i = 1, 2, ..., n.

Step 5. If convergence is achieved, stop; else set  $k \leftarrow k + 1$ , then go to step 2.

#### (4) Matlab 程式:

```
1
    clc
2
   clear all
   x=zeros(2,15);
   d=zeros(1,15);
 5
   x(1,:)=[1 2 2 2 3 3 4 5 5 5 6 7 8 8 9];
 6
   x(2,:)=[253245656786498];
7
   d=[2 1 2 2 1 3 2 3 4 3 4 2 4 3 4];
 8
   Cx = x * x ' / 15;
9
   lr0=0.9/max(eig(Cx));
   tau=200;
10
11 w=zeros(2,1);
12 b=zeros(1,1);
13 t=0;
14 cw=10000;
15
   a=0:cw-1;
16
   for j=1:cw
17
        t=t+1;
18
        lr(t)=lr0/(1+t/tau);
19
        for i=1:15
20
            y=x(1,i)*w(1)+x(2,i)*w(2)+b;
21
            yo(j)=y;
22
            e=d(i)-y;
23
            eo(j)=e;
24
            w=w+lr(t)*e*x(:,i);
25
            wo(:,j)=w;
26
            b=b+lr(t)*e;
27
            bo(j)=b;
28
        end
29
    end
30
   subplot(2,2,1)
31 plot(a,yo)
32
   axis([-inf,inf,-7,7])
33
   xlabel('次數');
   title('實際輸出值');
34
35
   subplot(2,2,2)
36 plot(a,eo)
37
   axis([-inf,inf,-7,7])
38
   xlabel('次數');
39
    title('實際誤差值');
40
```

說明:

Cx = x \* x' / 15;

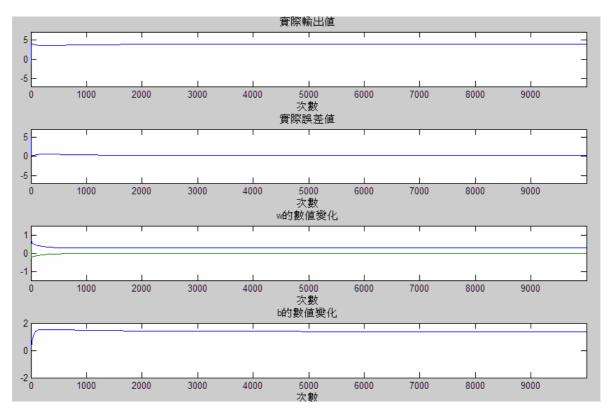
x\*x'是求出共變異矩陣,而除以15則是要算出平均值,此項計算便於 下個步驟求出eigen value所做的矩陣計算

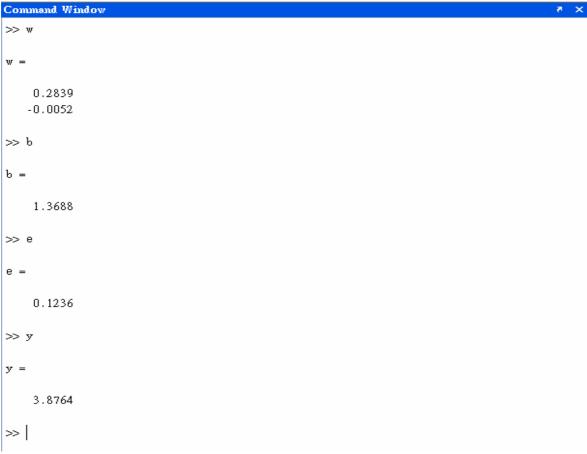
lr0=0.9/max(eig(Cx));

lr0做的計算則是初始學習速率,eig(Cx)則是將共變異矩陣求出eigen value,再利用max函數求得最大之eigen value。lr0所計算出來之數值 為下列公式之 $u_0$ 。

$$\mu(k) = \frac{\mu_0}{1 + k/\tau}$$

### (5) 模擬結果:

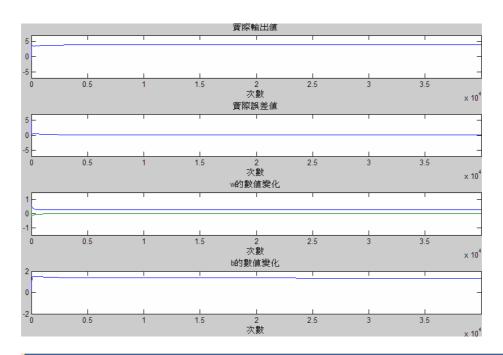


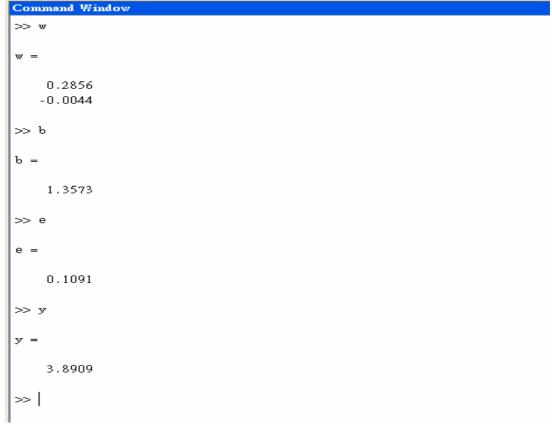


## (6) 討論:

1. 學習次數對輸出結果之影響(上述測試以10000次學習討論)

學習次數調整為 40000 次之結果





結論:學習次數越高,可讓 w 和 b 值學習更精準。但對收斂速度無幫助。

#### 2. 學習率、tau 值的關係:

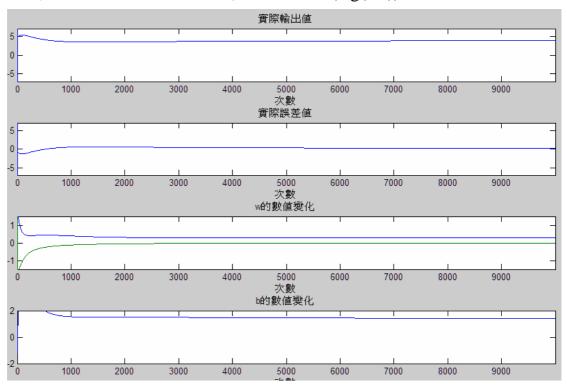
$$\mu(k) = \frac{\mu_0}{1 + k/\tau}$$

Where  $\mu$  is learning rate with  $0 < \mu < \frac{2}{\lambda_{max}}$  or  $0 < \mu < \frac{2}{\operatorname{trace}\{C_x\}}$ 

$$w(k+1) = w(k) + \mu[-\nabla_w J(w)] = w(k) + \mu e(k)x(k)$$

所求得之 lr0 為  $u_0$ , w 每次更新為前一次數值+學習率\*誤差值 \*輸入值,但因學習率會受到 k 的執行次數影響,而降低學習率,因此 w 所更新的值也越來越小,而 tau 也會直接影響至學習率,tau 越大,學習率越大,學習率越大,w 的更新值越大,也較難收斂。

#### 下列數值以tau=500, lr0設為lr0=1.5/max(eig(Cx))



由此圖可看出,tau及lrO越大,學習率較大,需較長時間才能

收斂。至於學習率為何會定義右邊公式原因:

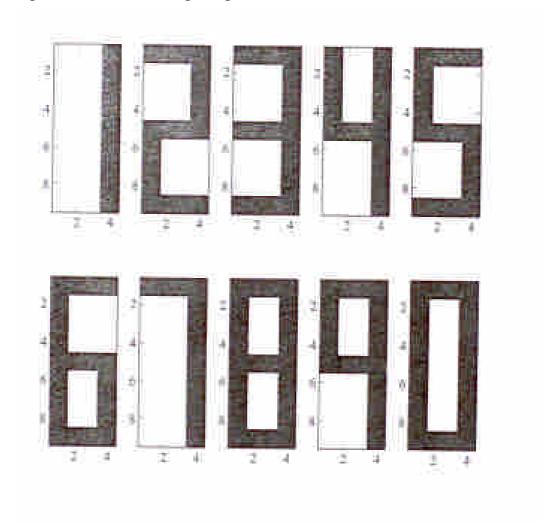
$$0<\mu<\frac{2}{\lambda_{max}}$$

U的大小會決定權重更新步伐,如果u太小則

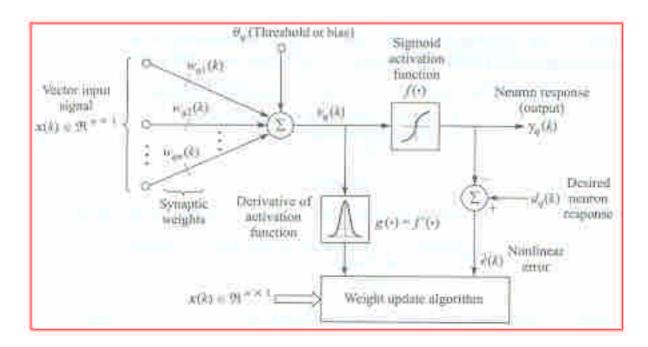
權重改變量也較小,太大則是造成目標發生振盪,因此Haykin建議u 在右上之範圍為最好。

# **Problem 2**

Q2: Use the simple perception with the sigmoid function to learn the digital 0~9 shown in right figure. (Use one neuron)



#### (1) 架構圖:



#### (2) 數學方程式:

#### Step 1. feed forward computation

$$\tilde{e}_q(k) = d_q(k) - v_q(k)$$

$$y_q(k) = f[v_q(k)]$$
  
=  $f\left[\sum_{j=1}^{n} x_j(k)w_{qj}(k) + \theta_q\right]$ 

#### Step 2. feedback learning

$$\begin{split} w_q(k+1) &= w_q(k) + \mu \alpha \tilde{e}_q(k) \big[ 1 - y_q^2(k) \big] x(k) \\ \text{or} \\ w_{qj}(k+1) &= w_{qj}(k) + \mu \alpha \bar{e}_q(k) \big[ 1 - y_q^2(k) \big] x_j(k) \\ \text{where } j = 1, 2, \dots, n. \end{split}$$

#### ALIES ! Binary sigmoid function 0.0 #\*(0;f $y_q = f_{bs}(v_q) = \frac{1}{1}$ 97 n a 12.5 Binary sigmoid 0.4 function Where a is the slope parameter 013 812 The function is continuous and differentiable

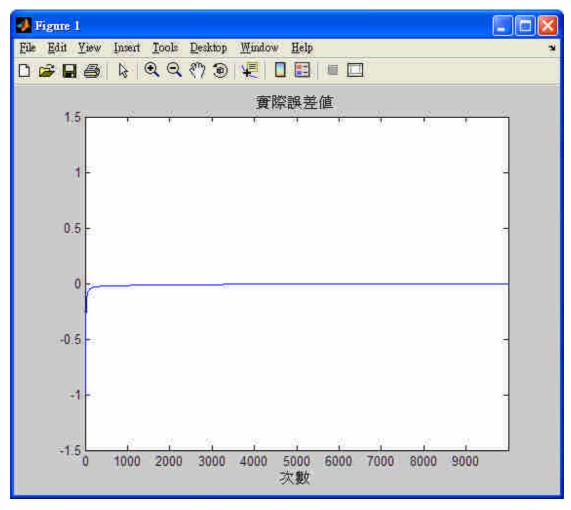
#### (3) Matlab 程式:

```
1 -
  cle:
2 -
  clear all
  4
   5
   6
   7
   9
   10
   11
   13 -
  w=rand(40,1);
14 -
  sa=0.05:
15 -
  d=[0.9 \ 0.8 \ 0.7 \ 0.6 \ 0.5 \ 0.4 \ 0.3 \ 0.2 \ 0.1 \ 0];
16 -
  a=0.5; u=0.25;
17 -
  mh=10000;
18 -
  xa=0:mh-1:
19 -
  for j=1:mh
20 -
    for i=1:10
21 -
     v=x(i,:)*w+sq:
22 -
     y=1/(1+exp(-a*v));yo(j)=y;yt(i)=y;
23 -
     e=d(i)-y;eo(j)=e;et(i)=e;
24 -
     w=w+u*a*e*(1-(y^2))*x(i,:)';
25 -
    end
26 -
  end
27 -
  plot (xa,eo,'b')
28 -
  axis([-inf, inf, -1.5, 1.5])
29 -
  xlabel('次數');
30 -
  title('實際誤差值');
```

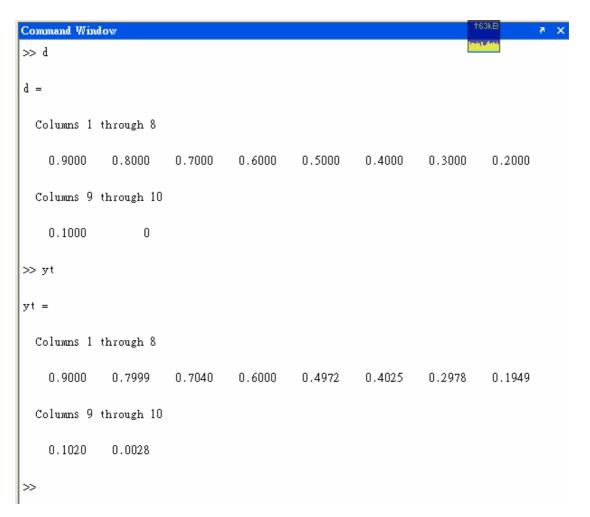
說明: x 為 10\*40 矩陣,設 i 為圖片數,則 x(I,:)為第 i 張圖片之輸入 訊號,而 w 為 40\*1 之矩陣, sq 為 sita q、d 為期望值、a 為 afa、u 為

學習率,學習次數為 10000 次。運算式採用 Binary sigmoid function 方式計算。

#### (4) 模擬結果:



實際誤差圖

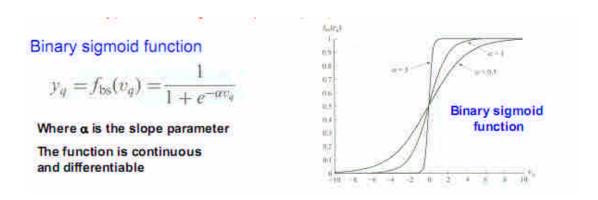


#### d 為期望值、yt 為記錄最後輸出值

eo											
	9990	9991	9992	9993	9994	9995	9996	9997	9998	9999	10000
1	-0.0028428	-0.0028425	-0.0028422	-0.0028419	-0.0028416	-0.0028413	-0.002841	-0.0028407	-0.0028403	-0.00284	-0.002839
2											
3											
4											
	<										

誤差值在接近 10000 次運算時的數值

#### (5) 討論:



#### Step 1. feed forward computation

$$\tilde{e}_q(k) = d_q(k) - y_q(k)$$

$$y_q(k) = f[v_q(k)]$$
  
=  $f\left[\sum_{j=1}^{n} x_j(k)w_{qj}(k) + \theta_q\right]$ 

#### Step 2. feedback learning

$$\begin{aligned} w_q(k+1) &= w_q(k) + \mu \alpha \tilde{e}_q(k) \big[ 1 - y_q^2(k) \big] x(k) \\ \text{or} \\ w_{qj}(k+1) &= w_{qj}(k) + \mu \alpha \tilde{e}_q(k) \big[ 1 - y_q^2(k) \big] x_j(k) \\ \text{where } j &= 1, 2, \dots, n. \end{aligned}$$

#### 1. afa 值的影響:

由Binary sigmoid function看出afa越小,則 exp(-a\*v)越小,但輸出值y會越大。afa越小則會影響到 w的更新權值。

### 2. sita q 的影響:

sita q越小, vq也會變小,而 vq變小後,經過 Binary sigmoid function 運算後,進而影響至輸出 值 y 會變大。

#### 3. u 的影響:

u越小則會影響到w的更新權值。

### 實驗:

將afa設為0.1、sita q=0.05、u=0.01,可從下圖看出收斂速 度明顯慢了好幾倍。

